

ECE201 Linear Systems

HW 10 - Solution

1] Show: $\det([AB]) = \det(A)\det(D)$

$$2 \times 2 \text{ case: } \det\begin{bmatrix} a & b \\ 0 & d \end{bmatrix} = \det(a)\det(d)$$

$n \times n$ case: Let $\begin{bmatrix} A_{n-1} & B_{n-1} \\ 0 & D_{n-1} \end{bmatrix}$ denote an $(n-1) \times (n-1)$ matrix and suppose

$$\det\begin{bmatrix} A_{n-1} & B_{n-1} \\ 0 & D_{n-1} \end{bmatrix} = \det(A_{n-1})\det(D_{n-1}) \quad \forall A_{n-1} \in \mathbb{C}^{m \times m}, B_{n-1} \in \mathbb{C}^{m \times p},$$

and $D_{n-1} \in \mathbb{C}^{p \times p}$, where $n-1 = m+p$.

Let $\begin{bmatrix} A_n & B_n \\ 0 & D_n \end{bmatrix}$ denote an $n \times n$ matrix, where $A_n \in \mathbb{C}^{(n+1) \times (m+1)}$,

$B_n \in \mathbb{C}^{(m+1) \times p}$, $D_n \in \mathbb{C}^{p \times p}$ and $n = m+p+1$.

$$\begin{aligned} \text{Then: } \det\begin{bmatrix} A_n & B_n \\ 0 & D_n \end{bmatrix} &= \sum_{k=1}^{m+1} [A_n]_{k,1} (-1)^{k-1} A_n \begin{pmatrix} 1 & \dots & k-1 & k+1 & \dots & m+1 \\ 2 & \dots & k & k+1 & \dots & m+1 \end{pmatrix} \det(D_n) \\ &= \det(A_n) \det(D_n). \end{aligned}$$

2] $\dot{z} = Az + bu$, $y = c^T z$, $z(0) = 0$.

$$Z_g^{(k)}(s) = \left[\frac{\gamma_{l_k}^{(k)}}{(s-\lambda_k)^{l_k-g+1}} + \frac{\gamma_{l_k-1}^{(k)}}{(s-\lambda_k)^{l_k-g}} + \dots + \frac{\gamma_8^{(k)}}{s-\lambda_k} \right] \cdot u(s)$$

$$\Rightarrow Z_g^{(k)}(t) = \left[\frac{\gamma_{l_k}^{(k)} t^{l_k-g} e^{\lambda_k t}}{(l_k-g)!} + \frac{\gamma_{l_k-1}^{(k)} t^{l_k-g-1} e^{\lambda_k t}}{(l_k-g-1)!} + \dots + \gamma_8^{(k)} e^{\lambda_k t} \right] * u(t)$$

$$\begin{aligned} \Rightarrow h(t) &= \sum_{k=1}^p \sum_{g=1}^{l_k} \delta_g^{(k)} Z_g^{(k)}(t) = \sum_{k=1}^p e^{\lambda_k t} \sum_{g=1}^{l_k} \delta_g^{(k)} \sum_{m=0}^{l_k-g} \frac{\gamma_{g+m}^{(k)}}{m!} \frac{t^m}{m!} \\ &= \sum_{k=1}^p e^{\lambda_k t} \sum_{m=0}^{l_k-1} \frac{t^m}{m!} \sum_{g=1}^{l_k-m} \delta_g^{(k)} \gamma_{g+m}^{(k)} \end{aligned}$$

$\Rightarrow H(s)$ is irreducible iff $\delta_g^{(k)} \neq 0$ and $\gamma_{l_k}^{(k)} \neq 0$, $k=1, \dots, p$.

(i.e. $\{A, b, c\}$ is

contr. + obs.)